



Dr. SRINIVASA RAO PUNDRU

Academic Expert

Academic Reputation of Times Higher Education 2025, 2024, 2023 & 2022

(Selected based on record of research publication)

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Mahatma Gandhi Institute of Technology [INDIA]

BIOGRAPHY:

“Dr. SRINIVASA RAO PUNDRU” has won the title of SCOPUS INDEX CONCLAVE 2025 Under “INTERNATIONAL BEST RESEARCHER AWARD” for the excellence of Mechanical Engineering (Robotics), as “International Multidisciplinary Innovations & Research Advancements Congress 2025” (IMIRAC 2025) awarded by ASIA RESEARCH AWARDS. “Dr. SRINIVASA RAO PUNDRU” from India affiliated to Mahatma Gandhi Institute of Technology [INDIA]. **He** was awarded the Doctor of Philosophy in Mechanical Engineering (Robotics) at Jawaharlal Nehru Technological University Kakinada [INDIA]. **He** completed Master of Engineering in Machine Design at Andhra University [INDIA]. **He** is an Academic Expert of World University Rankings and have been selected as a Recognized Researcher in Times Higher Education “World University Rankings”, based on his record of research publications. Universities cannot make nominations of Academic Experts. Universities cannot supply contact lists of Academic Experts. Individuals cannot nominate themselves for participation as Academic Experts. The Academic Experts selection is based on "The World latest Research data". Researchers are recognized based on record of research publications. World Research

Leading Countries Ranks are based on Research Leadership Index (RLI) Score, which is analyzed based on Record of Research Publication RLI Score of the articles. **He** submitted the highly confidential reports to Academic Reputation of Times Higher Education "World University Rankings" in respective Years 2025, 2024, 2023 & 2022. All his published research articles are Cross referred and Scopus. All his Springer articles are promoted to Cross reference appendix, Scopus appendix, and also all his published Springer articles are promoted externally to NASA and incorporated by NASA Astrophysics Data System. **His** Springer published articles are promoted to Harvard University and Researcher App. **He** was a **Keynote Forum Speaker** in "The 11th Annual World Congress of Ocean (WCO-2023)" – The 21st Conference on International Exchange of Professionals – Parallel Session in Japan and Cluster Meeting of Gala Technology 2023 on November 15-17, 2023, **JAPAN**. URL: <https://www.researchgate.net/publication/381703299> The 8th Annual Global Congress of Knowledge Economy GCKE Conference Sapporo Japan 2023 **He** was a **Distinguished Speaker** in "Global Congress on Advanced Satellite Communications 2023" Organized by Peers Alley Media 2023 on November 16, 2023 Venue: **CANADA**. URL: <https://www.peersalleyconferences.com/assets/main/reader/web/viewer.html?file=https://peersalley.s3.amazonaws.com/assets/conference-book/adv-satellite-2023-185-115.pdf> **He** was a **Distinguished Speaker** in Appl SciMeet 2025, SCI SYNOPSIS, "European Meeting on Applied Science and Engineering", **Berlin, GERMANY** on April 14-15, 2025 URL: https://scisynopsisconferences.com/uploads/conferences/applied-science_99/Applied%20Science%202025%20Book.pdf **He** was a **Distinguished Speaker** in "European Congress on Applied Science and Engineering", C2P Forum, **Paris, FRANCE** on April 24-25, 2025 URL: <https://c2pforum.com/conferences/uploads/conferences/1745414744.pdf> **He** was a **Plenary Speaker** in The ICONIC Meetings on "International Experts Summit on Aerospace and Aeronautics Engineering", **Valencia, SPAIN** on May 26-28, 2025 URL: https://www.aerospace.theiconicmeetings.com/Viewproceedingbooks/viewFile/5/program_book URL: https://www.aerospace.theiconicmeetings.com/Viewproceedingbooks/viewFile/5/abstract_book **He** Won **Nobel Researcher Award** in the field of Mechanical in "Scientific Laurels International Scientific Awards" on 5th June 2025 URL:

<https://scientificlaurels.com/biography/peJf> He was a Special Speaker in “Annual International Congress on Mechanical Engineering” **Oxford, United Kingdom** (AICME-2025) on August 7-8, 2025 and Certificate ID: 1AICME2685

URL: <https://mechrtc.com/wp-content/uploads/2025/08/Conference-Program-MechRTC.pdf> and

URL: <https://mechrtc.com/wp-content/uploads/2025/08/Proceeding-of-Annual-International-Conference-on-Mechanical-Engineering.pdf> He Won Research Vibhushan Award 2021 in the field of Mechanical Engineering on 15th August 2021, Award received from ISSN - ISSN Awards 2021-.International Research Vibhushan Award. URL:

(<https://oxfordresearchnews.com/2021/08/26/dr-pundru-srinivasa-rao/>) and URL:

<https://www.youtube.com/watch?v=SAQ0-leG5tc> “**Dr. SRINIVASA RAO PUNDRU**”

Published Research articles links @ Harvard University and NASA URL’s:

<https://ui.adsabs.harvard.edu/abs/2025JIEIC.tmp..113P/abstract>

<https://ui.adsabs.harvard.edu/abs/2024JIEIC.105..195P/abstract>

<https://ui.adsabs.harvard.edu/abs/2021JIEIC.102..209P/abstract>

<https://ui.adsabs.harvard.edu/abs/2019JIEIC.100.1031P/abstract>

<https://ui.adsabs.harvard.edu/abs/2022JIEIC.103.1083R/abstract>

<https://ui.adsabs.harvard.edu/abs/2022JIEIC.103.1447P/abstract>

“**Dr. SRINIVASA RAO PUNDRU**” published “**Workspace Analysis of Calibrated Multi-position Synthesized 3-Prismatic-Revolute-Spherical Manipulator**”, J. Inst. Eng. India Ser. C (Print ISSN 2250 – 0545), (online ISSN 2250-0553), Vol. 105, Issue 01, February 2024, pp 195-214, URL

<https://doi.org/10.1007/s40032-023-01017-9> **ScImago, SCOPUS , SPRINGER, Citation Rank**

22nd Percentile, ORCID ID: <http://orcid.org/0000-0001-5937-3694> **ORCID: Works:**

Source: Crossref. He published “**Synthesis of Multi-position 3-PRS Manipulator based on Spherical Constraints by Eliminating the Parasitic Motion**”, J. Inst. Eng. India Ser. C (Print ISSN 2250 – 0545), (online ISSN 2250-0553), Vol. 103, Issue 06, December 2022, pp 1447-1454, URL <https://doi.org/10.1007/s40032-022-00887-9> **ScImago, SCOPUS , SPRINGER, Citation Rank 50th Percentile**, ORCID ID: <http://orcid.org/0000-0001-5937-3694> **ORCID: Works: Source: Crossref.** He published “**Calibrating a Synthesized 3-PRS Manipulator by Minimizing the Errors in Positions of Revolute Joints**”, J. Inst. Eng. India Ser. C (Print ISSN 2250 – 0545), (online ISSN 2250-0553), Vol. 103, Issue 05, October 2022, pp 1083-1093, URL

<https://doi.org/10.1007/s40032-022-00866-0> **ScImago, SCOPUS , SPRINGER, Citation Rank**

57th Percentile, ORCID ID: <http://orcid.org/0000-0001-5937-3694> **ORCID: Works:**

Source: Crossref. He published “Synthesis of 3-PRS Manipulator Based on Revolute and Cone Angle of Spherical Constraints on Range of Rotational Motion of Spherical Joints”, J. Inst. Eng. India Ser. C (Print ISSN 2250 – 0545), (online ISSN 2250-0553), Vol. 102, Issue 01, February 2021, pp 209-219 <https://doi.org/10.1007/s40032-020-00599-y> **SCImago, SCOPUS, SPRINGER, Citation Rank 66th Percentile**, ORCID ID: <https://orcid.org/0000-0001-5937-3694> **ORCID: Works: Source: Crossref.** He published “Synthesis of multi-positions 3-prismatic-revolute-spherical manipulator”, J. SN Appl. Sci. (Print ISSN 2523-3963), (online ISSN 2523-3971), September 2019, 1:1114. <https://doi.org/10.1007/s42452-019-1085-0> **SCImago, SCOPUS, Web of Science, SPRINGER NATURE, Citation Rank 66th Percentile** Web of Science Researcher ID: <AAI-2404-2020> ORCID ID: <http://orcid.org/0000-0001-5937-3694> **ORCID: Works: Source: Crossref.** He published “Synthesis of 3-PRS Manipulator Using Exact Method”, J. Inst. Eng. India Ser. C (Print ISSN 2250 – 0545), (online ISSN 2250-0553), Vol. 100, Issue 06, December 2019, pp 1031-1042 <https://doi.org/10.1007/s40032-018-0499-6> **SCImago, SCOPUS, SPRINGER, Citation Rank 72nd Percentile**, ORCID ID: <http://orcid.org/0000-0001-5937-3694> **ORCID: Works: Source: Crossref.** He published “Spatial Three Degree of Freedom Parallel Manipulator Forward Kinematic Position Analysis”, International Journal of Engineering & Technology(UAE), (ISSN 2227 – 524X) Vol. 7, No. 4.5, 2018, pp 147-150 <https://doi.org/10.14419/ijet.v7i4.5.20032> **SCOPUS.** He published “Three Degree of Freedom Spatial Parallel Manipulator Inverse Kinematic Position Analysis”, International Journal of Engineering & Technology(UAE), (ISSN 2227 – 524X) Vol. 7, No. 4.5, 2018, pp 98-101 <https://doi.org/10.14419/ijet.v7i4.5.20020> **SCOPUS.** His Springer Published research articles are “**Scopus** and **CrossRef** with **Citation Ranks**”. All his recognized Research articles are published in Springer Journal at Free of Cost @ no Publication Charges in “**Scopus and CrossRef with Citation Ranks**”. He was selected as a **Plenary, Distinguished, Keynote Speaker** at various International Recognized Forums and they **granted 100% registration fee waiver approved** as a mark of respect to his Academic Contributions. **Dr. SRINIVASA RAO PUNDRU Research Inspiration:** Clarivate Analysis of “Research Fronts-Active Fields-Leading Countries”. **His Research Level:** A part of “**Times Higher Education Global Academic Reputation 2025, 2024, 2023 & 2022 Academic Expert**” and have been selected based on record of research publications. **2025:** URL <https://www.iffresearch.com/go/J13412> and **ID highly confidential** provided by Times Higher Education Global Academic Reputation 2025 in partnership

with Elsevier. **2024:** URL <https://www.iffresearch.com/go/J12840> and **ID highly confidential** provided by Times Higher Education Global Academic Reputation 2024 in partnership with Elsevier. **2023:** URL <https://www.iffresearch.com/go/J12167/> and **ID highly confidential** provided by Times Higher Education Global Academic Reputation 2023 in partnership with Elsevier. **2022:** URL <https://www.iffresearch.com/go/j11588/> and **ID highly confidential** provided by Times Higher Education Global Academic Reputation 2022 in partnership with Elsevier. **His Task of Research Goal** is to increase the “Research Leadership Index (RLIC) Score of the Country”. The Country Economic development along with the growth of local Currency are based on RLI (Research Leadership Index) Score of the record of research publications of the Country and are analyzed by Clarivate Analysis of “Research Fronts-Active Fields-Leading Countries”.

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